

Progress in Dynamic Texture Showcase

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- 1 Visual motion and dynamic texture
- 2 Dynamic texture detection
 - Regular and nonregular optical flows
 - Segmentation using regular and nonregular flows
- 3 Results
- 4 Available versions of algorithm
- 5 Summary

Categories of visual motion patterns

- Activities

- periodic in time, localised in space
⇒ walking, digging

- Motion events

- no temporal or spatial periodicity
⇒ opening a door, jump

- Temporal textures

- statistical regularity, indeterminate spatial and temporal extent
⇒ fire, smoke

Examples of dynamic textures



regular



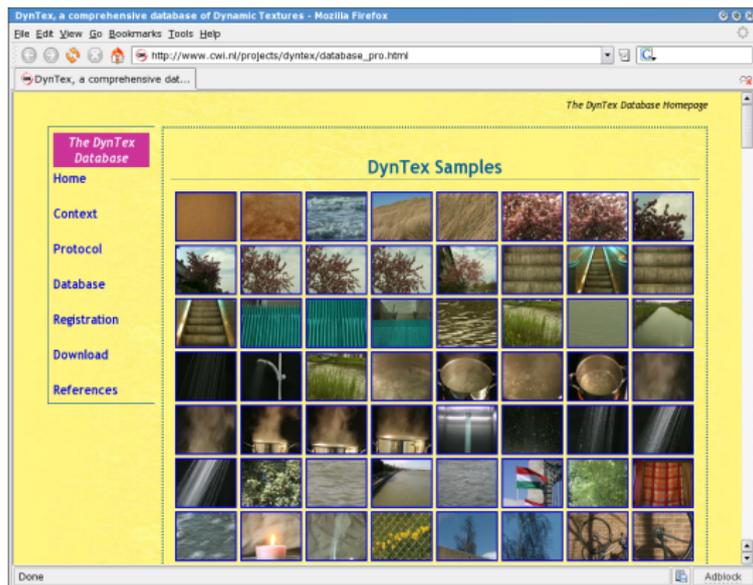
disturbed



mixed

⇒ show sample videos

DynTex database by NoE MUSCLE



- 656 digital videos
- PAL 720 x 576, 25 fps
- Length \geq 250 frames
- Closeups and contexts
- Static/moving camera
- Indoor and outdoor natural scenes
- Annotated, categorised (**work in progress**)
- Available on the Web (\approx 50 registered users)

<http://www.cwi.nl/projects/dyntex/>

(In collaboration with **R. Péteri**, **M. Huiskes**, and **CWI**)

Non-regular optical flow for dynamic texture

- Work in progress with Tel-Aviv University (TAU)
 - Tomer Amiaz
 - Nahum Kiryati
- Dynamic textures have strong **intrinsic dynamics**
 - motion cannot be compensated by shift/rotation
 - **intensity constancy** assumption not valid
 - standard (regular) optical flow not precise
- Use **intensity conservation** assumption instead
 - non-regular optical flow with divergence term
 - intensity may diffuse
- Dynamic texture detection
 - segmenting flow into regular and non-regular part
 - indicator function in level-set implementation

Brightness conservation assumption

- **Non-regular optical flow** (compared to Horn-Schunck)

$$\text{Brightness constancy: } I(x + u, y + v, t + 1) = I(x, y, t)$$

$$\text{Optical flow constraint: } I_t + uI_x + vI_y = 0$$

$$\text{Brightness conservation: } I(x + u, y + v, t + 1) = I(x, y, t)(1 - u_x - v_y)$$

$$\text{Continuity equation: } I_t + uI_x + vI_y = -I \cdot (u_x + v_y)$$

- Brightness of an image point (in one frame) can propagate to its neighborhood (in the next frame)
- Captures more information than a regular flow
- Encodes the warp residual of a regular flow
- Applicable to strong dynamic textures (**generic feature**)

- Horn-Schunck

- brightness constancy ($\mathbf{v} = (u, v)$: velocity vector)

$$\partial_t I + \mathbf{v} \cdot \nabla I = 0$$

- Lagrangian

$$L_{HS}(u, v) = (I_t + uI_x + vI_y)^2 + \alpha(u_x^2 + u_y^2 + v_x^2 + v_y^2)$$

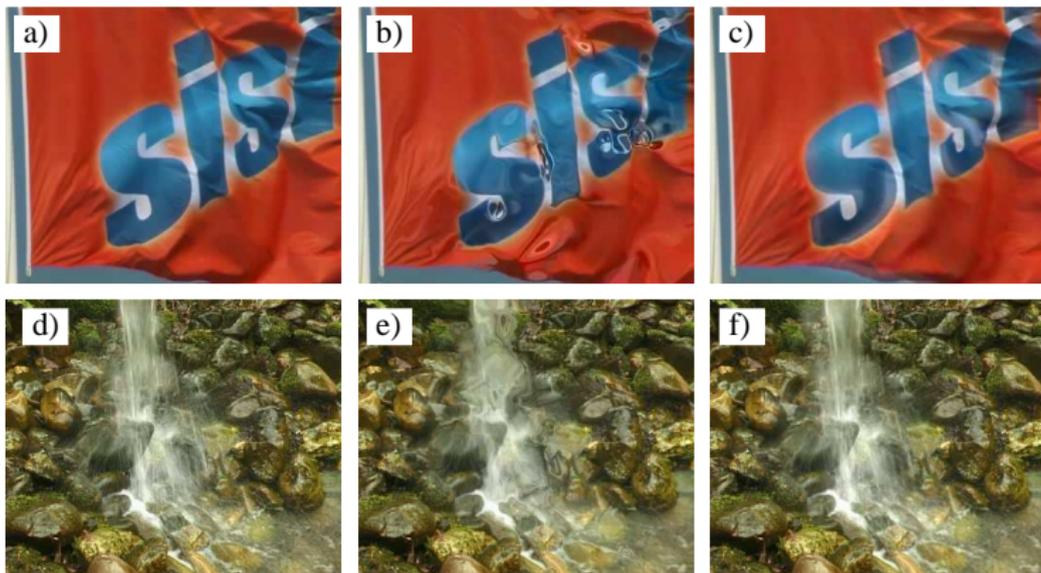
- minimise $F_{HS}(u, v) = \int_I L_{HS}(u, v) dx dy$

- Brightness conservation

$$\partial_t I + \mathbf{v} \cdot \nabla I + I \operatorname{div} \mathbf{v} = 0$$

- Lagrangian more complicated, but essentially similar

More precise motion compensation by nonregular flow



(a,d): frame 1 of dynamic texture; (b,e): frame 2 warped back by regular flow; (c,f): same by non-regular flow

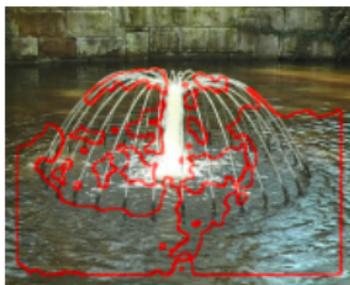
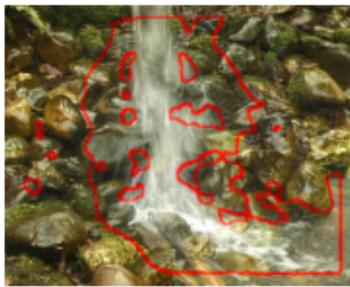
- **Segmentation** as a **variational problem**

$$\begin{aligned} L_{DTS}(u, v, \tilde{u}, \tilde{v}, \phi) = & \\ & (I_t + uI_x + vI_y)^2 H(\phi) + (I_t + \tilde{u}I_x + \tilde{v}I_y + I\tilde{u}_x + I\tilde{v}_y)^2 H(-\phi) \\ & + \alpha(u_x^2 + u_y^2 + v_x^2 + v_y^2) + \tilde{\alpha}(\tilde{u}_x^2 + \tilde{u}_y^2 + \tilde{v}_x^2 + \tilde{v}_y^2) + \tilde{\beta}(\tilde{u}^2 + \tilde{v}^2) \\ & + \nu |\nabla H(\phi)| \end{aligned}$$

$$F_{DTS}(u, v, \tilde{u}, \tilde{v}, \phi) = \int_I L_{DTS}(u, v, \tilde{u}, \tilde{v}, \phi) dx dy$$

- Brightness **constancy** on static and weak dynamic regions
- Brightness **conservation** on strong dynamic regions
- Smooth boundary of segmented regions
- **Solved** (Euler-Lagrange eqs., discretisation based on central derivatives, iterative solver, ...)

Results



⇒ show sample videos

Versions: Making it faster

- Full algorithm
 - precise segmentation
 - no thresholding needed (decision by indicator function)
 - currently, slow (15–20 sec/frame)

⇒ make faster using graph cuts
- Fast simplified version
 - less precise segmentation
 - threshold learned, then adjusted adaptively
 - close to real-time (5–10 fps)
- Real-time simplified version
 - less precise segmentation, sometimes errs
 - threshold adjusted adaptively
 - real-time (20–25 fps)

- Collaborative work of **SZTAKI** and **TAU**
- Showcase with **Bilkent**
- **Generic method** for detecting dynamic textures
 - processes of various physical origin
- More than just detection/segmentation
 - calculates optical flow useful for **recognition**
- Plans
 - speed up full algorithm (graph cuts)
 - improve real-time version: automatic threshold, adaptivity
 - distinguish between DTs and other fast motion
 - integrate with periodicity detection and DT recognition